# Numerical Studies of Coal Bed Fracturing 

## for Effective Methane Drainage

Andrey V. Patutin*, Petr A. Martynyuk and Sergey V. Serdyukov<br>Institute of Mining, Siberian Branch, Russian Academy of Science 54 Krasnyi, Novosibirsk, 630091 Russia

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#### Abstract

An effective methane drainage from the coal seam is essential for safety mining operations. This paper describes the algorithm used for calculating trajectory of crack formed by the hydraulic fracturing carried out in parallel wells. The results of numerical analysis show that direction of crack propagation is affected by the pressure applied and surrounding rock's stress state. The maximum possible distance between hydraulically fractured wells at which they linked was estimated. The obtained results help to design hydraulic fracture treatments in coal measure rocks in order to solve the problem of underground methane production or intensification of beds degassing.


Keywords: numerical modeling, methane drainage, hydraulic fracturing control, coal bed methane.

## Introduction

One of the main challenges of underground coal mining is methane-bearing formations and sudden coal and gas outbursts related to them. The probability of catastrophic events of gas-dynamic processes increases with the depth of the coal seam. It is necessary to note that problems caused by high methane concentrations not only affect the safety of mining operations, but also the economic and environmental aspects of coal production.

Coal bed methane (CBM) extraction is complicated by low coal permeability, methane sorption (trapping) on the surface, water saturation, and various geological formations with natural or artificial fracture systems. There is a particular complexity in gas production during preliminary degassing. At this stage the coal bed is not affected by development, the channels for gas flow are not formed and the overall degassing operations are not efficient for methane removal from the coal measure. Due to these factors the risk of gas outbursts is still very high and the labor productivity is poor.

One of the main methods of CBM production stimulation is hydraulic fracturing which is used in wells drilled both from the surface and from the underground.

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## Statement of the problem

Simultaneous propagation of several fractures and, as a result, formation of main crack that will link several degassing wells is one of the main condition for efficient gas recovery. To achieve the goal it is necessary to solve the problem of wells positioning which is strongly affected by stress condition of coal measure.

There is a problem of determining the relative position of simultaneous fracturing wells under a given stress state of the coal measure rocks at the design stage of the degassing system.

To assess the control efficiency of a synchronous propagation of cracks we have developed special software that implements incremental algorithm for calculating quasi-static trajectories of cracks.

## Mathematical model and algorithm description

Solution to the problem based on the mathematical model which suggests propagation of $N$ smooth curvilinear cracks from the boundary of the circular hole with radius $R$. There is a uniform field of compressive stresses acting at infinity with intensity $p_{0}$ and $q_{0}\left(\left|p_{0}\right| \geq\left|q_{0}\right|\right)$. Let us consider the form of each cut $L_{k}$ in local coordinate system $x_{k} O_{k} y_{k}$ is known and determine by parametric equation:

$$
t_{k}=\omega_{k}\left(l_{k} \xi\right)=x_{k}(\xi)+i y_{k}(\xi) ; \quad|\xi| \leq 1 ; \quad t_{k} \in L_{k}
$$

Relationship between coordinates of points in the main and local systems is given by:

$$
z=x+i y=z_{k} \exp \left(i \alpha_{k}\right)+z_{k}^{0}=\left(x_{k}+i y_{k}\right) \exp \left(i \alpha_{k}\right)+x_{k}^{0}+i y_{k}^{0}
$$

where $\alpha_{k}$ angle between $O x$ и $O_{k} x_{k}$ axes, and $z_{k}^{0}$ - the origin of coordinates of local system in the main.

We seek a solution to the problem of elasticity theory, when normal and tangential stresses are known on the contours of the cuts:

$$
N_{k}^{ \pm}+i T_{k}^{ \pm}=p_{k}\left(t_{k}\right) ; \quad t_{k} \in L_{k} ; \quad k=\overline{1, N}
$$

The plus sign refers to the upper edge of the cut, and the minus sign to the bottom. There is a compressive stress field at infinity and stresses are determined at the contour of the cut (the pressure in the fracture is equal to $\sigma_{0}$ and its contour is stretched in the vertical direction by $\sigma_{y y}=\sigma_{00}$ ).

When integral expressions of complex potentials of stresses for a plane with a circular hole [1] are used the problem reduces to finding solutions $g_{k}{ }^{\prime}(\xi), \quad k=\overline{1, N}$ of the complex system consisting of $N$ singular integral equations:

$$
\frac{1}{2 \pi} \sum_{k=1}^{N} \int_{-1}^{1}\left[R_{k n}(\xi, \eta) g_{k}^{\prime}(\xi)+S_{k n}(\xi, \eta) \overline{g_{k}^{\prime}(\xi)}\right] d \xi=P_{n}(\eta) ; \quad|\eta| \leq 1 ; \quad n=\overline{1, N}
$$

where $g_{k}^{\prime}(\xi)=g_{k}^{\prime}\left(t_{k}\right) \omega_{k}^{\prime}\left(l_{k} \xi\right)$ and $g_{k}^{\prime}\left(t_{k}\right)$ - derivative of displacement shift

$$
\frac{d}{d t_{k}}\left[\left(u_{k}+i v_{k}\right)^{+}-\left(u_{k}+i v_{k}\right)^{-}\right]=\frac{i 4\left(1-v^{2}\right)}{E} g_{k}^{\prime}\left(t_{k}\right), \quad t_{k} \in L_{k}
$$

where $u_{k}, v_{k}$ horizontal and vertical edge displacements of the cut in the local coordinate system, $v-$ the Poisson's ratio, $E$ - modulus of elasticity of the medium. Kernels of the integral equations are:

$$
\begin{aligned}
& R_{k n}(\xi, \eta)=R_{k n}\left(T_{k}, T_{n}\right)=e^{i \alpha_{k}}\left(\zeta_{k n}(\xi, \eta)+\rho_{n} \cdot r_{k n}(\xi, \eta)\right) \\
& S_{k n}(\xi, \eta)=S_{k n}\left(T_{k}, T_{n}\right)=e^{i \alpha_{k}}\left(\overline{\zeta_{k n}(\xi, \eta)}+\rho_{n} \cdot s_{k n}(\xi, \eta)\right) \\
& T_{k}=T_{k}(\xi)=e^{i \alpha_{k}} \omega_{k}\left(l_{k} \xi\right)+z_{k}^{0} ; \quad T_{n}=T_{n}(\eta)=e^{i \alpha_{n}} \omega_{n}\left(l_{n} \eta\right)+z_{n}^{0} ; \\
& \rho_{n}=\frac{\overline{\omega_{n}^{\prime}(\eta)}}{\varpi_{n}^{\prime}(\eta)} \cdot e^{-2 i \alpha_{n}}, \quad A=1-T_{k} \overline{T_{k}}, \quad a 1=\overline{T_{n}} T_{k}-1, \quad a 2=T_{k}-T_{n}, \\
& \zeta_{k n}(\xi, \eta)=\frac{1}{a 2}+\frac{1}{T_{n} \overline{a 1}}+\frac{A}{T_{k} a 1^{2}}+\frac{1}{T_{n}} \\
& r_{k n}(\xi, \eta)=-\frac{2 T_{n} A}{a 1^{3}}+\frac{1}{\overline{a 2}}+\frac{1}{a 1 \overline{T_{n}}}+\frac{A\left(3 T_{k} \overline{T_{n}}-1\right)}{a 1^{3} T_{k} \overline{T_{n}^{2}}}+\frac{1}{\overline{T_{n}}} \\
& s_{k n}(\xi, \eta)=-\frac{a 2}{\overline{a 2^{2}}}+\frac{1}{\overline{T_{k}} \overline{T_{n}^{2}}}+\frac{3 T_{k} \overline{T_{n}}-2}{a 1^{2} \overline{T_{n}^{3}}}-\frac{T_{n}\left(2 T_{k} \overline{T_{n}}-1\right)}{a 1^{2} \overline{T_{n}^{2}}}+\frac{2-T_{n} \overline{T_{k}}}{\overline{T_{n}^{3}}} \\
& P_{n}(\eta)=-p_{n}(\eta)-\left\{p_{+}-p_{-} 2 \operatorname{Re}\left(\frac{e^{2 i \gamma}}{T_{n}^{2}}\right)+\rho_{n}\left[\frac{p_{+}+\sigma_{0}}{\overline{T_{n}^{2}}}+\right.\right. \\
& \left.\left.+p_{-}\left(\frac{2 T_{n} e^{-2 i \gamma}}{\overline{T_{n}^{3}}}-e^{2 i \gamma}-\frac{3 e^{-2 i \gamma}}{\overline{T_{n}^{4}}}\right)\right]\right\}-\sigma_{00}\left[2 \operatorname{Re}\left(\frac{1}{i \pi T_{n}} \ln \frac{T_{n}-i}{T_{n}+i}\right)+\right. \\
& \left.+\rho_{n}\left(\frac{1}{i \pi} \cdot \frac{\overline{T_{n}}\left(T_{n}+\overline{T_{n}}\right)-2}{\overline{T_{n}^{3}}} \cdot \ln \frac{\overline{T_{n}}+i}{\overline{T_{n}}-i}+\frac{2\left(T_{n} \overline{T_{n}}-1\right)}{\pi \overline{T^{2}}\left(1+\overline{T^{2}}\right)}\right)\right]
\end{aligned}
$$

where $p_{+}=\left(p_{0}+q_{0}\right) / 2 ; \quad p_{-}=\left(p_{0}-q_{0}\right) / 2$. As cracks begin to grow from the boundary of the hole, the kernels have the property $R_{k n}(-1, \eta)=S_{k n}(-1, \eta)=0$. Note that if the number of cracks is even, the central symmetry of the problem can be used, and it is possible to reduce he order of the equations system by half.

The solution for kernels of integral equations is sought in the form $g_{k}^{\prime}(\xi)=\varphi_{k}(\xi) / \sqrt{1-\xi^{2}}$; and using the Gauss quadrature formulas, the solution of integral equations system is reduced to solving a system of linear algebraic equations:

$$
\begin{aligned}
& \sum_{k=1}^{N} \sum_{i=1}^{N}\left[R_{k j}\left(\xi_{i}, \eta_{m}\right) \varphi_{k}\left(\xi_{i}\right)+S_{k j}\left(\xi_{i}, \eta_{m}\right) \overline{\varphi_{k}\left(\xi_{i}\right)}\right] d \xi=2 n P_{j}\left(\eta_{m}\right) \\
& j=\overline{1, N} ; \quad m=\overline{1, n-1}
\end{aligned}
$$

where $n$ is the order of approximation of solution and $\xi_{i}=\cos \frac{\pi(2 i-1)}{2 n}, i=\overline{1, n}$; $\eta_{m}=\cos \frac{\pi m}{n}, \quad m=\overline{1, n-1}$ are zeros of the Chebyshev polynomials $T_{n}(\xi)=\cos (n \arccos \xi)$, $U_{n-1}(\eta)=\frac{\sin (n \arccos \eta)}{\sqrt{1-\eta^{2}}}$ of first and second kinds respectively. Mathematical conditions that will ensure finiteness of displacement at the left end of the cut located on the border of the hole and will close the system of equations are $\varphi_{k}(-1)=0 ; \quad k=1, N$.

The values of the function $\varphi_{k}(\xi)$ at the ends of cuts are defined by the following equations:

$$
\begin{aligned}
& \varphi_{k}(-1)=\frac{1}{n} \sum_{i=1}^{n}(-1)^{i+n} \varphi_{k}\left(\xi_{i}\right) \operatorname{tg} \frac{\pi(2 i-1)}{4 n} \\
& \varphi_{k}(1)=-\frac{1}{n} \sum_{i=1}^{n}(-1)^{i} \varphi_{k}\left(\xi_{i}\right) \operatorname{ctg} \frac{\pi(2 i-1)}{4 n}
\end{aligned}
$$

where $\varphi_{k}\left(\xi_{k}\right)$ is the solution of system of equations at nodal points. Stress intensity factors at the tip of k-crack:

$$
K_{1 k}-i K_{2 k}=-\sqrt{\left|\omega_{k}^{\prime}(1)\right|} \frac{\varphi_{k}(1)}{\omega_{k}^{\prime}(1)}
$$

The limit equilibrium condition for any crack can be written as:

$$
K_{k}=\frac{1}{4} \cos ^{3}\left(\frac{\vartheta_{* k}}{2}\right)\left[K_{1 k}+3 \sqrt{K_{1 k}^{2}+8 K_{2 k}^{2}}\right]=\frac{K_{1 C}}{\sqrt{\pi}}
$$

where $K_{1 k}, K_{2 k}$ are stress intensity factors for the tip of $k$ crack, $K_{1 C}$ is critical stress intensity factor, and angle $\vartheta_{*_{k}}=2 \operatorname{arctg} \frac{K_{1 k}-\sqrt{K_{1 k}^{2}+8 K_{2 k}^{2}}}{4 K_{2 k}}$ determines the direction of further crack growth, which coincides with the plane on which the principal component of the tensile stress reaches its maximum value, and shear stresses are zero. This is also known as $\sigma_{\vartheta}$ criterion [2].

Crack opening displacement $[v]=v_{n}^{+}-v_{n}^{-}$along its path can be determined as:
where $l_{k}$ is the length of k crack, and function $\varphi_{k}(\xi)$ can be calculated through the known values in nodal points $\xi_{j}$ as follows:

$$
\varphi_{k}(\xi)=\frac{1}{n} \sum_{j=1}^{n}(-1)^{j+1} \varphi_{k}\left(\xi_{j}\right) \frac{T_{n}(\xi) \sqrt{1-\xi_{j}^{2}}}{\xi-\xi_{j}}
$$

Thus, we can find the crack or cracks, where limit equilibrium condition is satisfied. Then the stepwise algorithm for building quasi-static trajectories of fracture propagation is used. It has been tested and described in [3-5].

To estimate the efficiency of simultaneous fracture propagation caused by longitudinal hydraulic fracturing special software based on quasi-static approximation was developed. The program allows to calculate the trajectory depending on several factors:
a) the distance between centers of initial fractures $d$;
b) initial fractures length $l$;
c) stress state of coal bed, particularly maximum and minimum compressive stress components $p_{0}$ and $q_{0}$ respectively and their relation $q d p$;


Fig. 1. The initial position of cracks in the compressive field


Fig. 2. Calculation termination conditions
d) the angle gam between coalescence plane of adjacent cracks and maximum stress direction (Fig. 1).
It was assumed that there are five cracks in isotropic elastic plane with half length equal to one located on straight line along X coordinate; $p_{0}$ and $q_{0}$ were compressive stress components at infinity ( $p_{0}>q_{0}$ ) and the angle between maximum stress $p_{0}$ and initial cracks direction is gam. The fracture growth is provided with pressure applied to the initial cracks ( $e_{00} \times p_{0}$, where $e_{00}>0$ ).

According to the software algorithm, the count stopped when growing fractures approached each other closer than $a x_{\text {crit }}$ or one of fracture wings came out from the $a y_{\text {crit }}$ interval (Fig. 2). These critical values were obtained during auxiliary studies covered the process of fractures interaction and coalescence on relatively small ranges.

The limitation for $a x_{\text {crit }}$ can be explained due to certain features of used software: the algorithm is not designed for modeling of fractures intersection. That is why the value of $a x_{\text {crit }}$ was chosen small enough to consider separate cracks as a jointed system. The reason for $a y_{\text {crit }}$ limit is due to the fact that cracks do not merge during the fracturing when they are out of $\pm a y_{\text {crit }}$ interval.

The purpose of numerical studies was to determine the maximum distance between fracturing wells $d_{\max }$ at which separate cracks merge into a single system, and to estimate the impact of various factors on this value.

## Numerical experiments and results

Numerical experiments were carried out as follows:
a) $q d p$ value was chosen equal to 0.5 or 0.8 ;
b) angle gam was chosen equal to $10,30,45,60$ or 80 degrees;
c) the ratio of pressure in the crack to the maximum compressive stress $e_{00}$ varied in the range from 1.2 to 10.0 ;


Fig. 3. Dependence of $d_{\max }\left(e_{00}\right)$ for different angles: a) $q d p=0.8$ and b) $q d p=0.5$
d) $a x_{c r i t}=0.05 ; a y_{c r i t}=1$

During experiments the desired value of $d_{\max }$ was determined.
Fig. 3 shows the calculated dependence of the maximum distance $d_{\max }$ on the $e_{00}$ when $q d p$ value equal to 0.8 and 0.5 respectively.

Presented graphs show that with increasing pressure in the cracks there is a growth in the distance $d_{\max }$. According to the data obtained this growth is faster when the angle gam getting closer to the direction of one of the principal stresses. The total dependence of $d_{\max }\left(e_{00}\right)$ is given by $d_{\max }=A \times \ln \left(e_{00}\right)+B$ with high degree of approximation and correlation coefficient $\mathrm{R}^{2}>0.99$.

When the relation $q d p$ is decreased, the maximum distance between wells $d_{\max }$ becomes smaller. Another feature is that in the non-uniform compression field this spacing is less than in the hydrostatic (or uniform) condition. With decreasing angle gam from $80^{\circ}$ to some gam $_{\text {crit }}$, the value of $d_{\max }$ is reduced, and a further decrease leads to gam value growth. Fig. 4 shows the dependence of the gam $_{\text {crit }}$ on $q d p$, based on the numerical experiments results. The value of gam $_{\text {crit }}$ increases linearly from $36^{\circ}$ at $q d p$ equals 0.5 to $44^{\circ}$ with $q d p$ equals 0.9 ; and approximate value for the critical angle is $45^{\circ}$ when the stress state of coal measure rocks can be described as hydrostatic.

Overall, these results are consistent with the generally accepted linear fracture mechanics, which confirms the correctness of the algorithm and software program.

Fig. 5 shows a plot of $d_{\max }$ dependent on $e_{00}$ at different $q d p$. The angle between the direction of the maximum principal stress and the fracture line is either equal to $1^{\circ}$, or close to $90^{\circ}$.

In this case, when the direction of cracks propagation is close to the direction of one of the principal stresses, the formation of a combined fracture system is performed at the greatest distances between fracturing wells. The maximum value of $d_{\max }$ is observed during the cracks propagation in the less energetically favourable direction ( gam equal to $89^{\circ}$ ) which is corresponds to a minimum principal stress.

The results show a strong influence of the hydraulic fracturing pressure on the crack propagation stability in a given direction. At small pressures, which can be modeled by low pumping rates of fluid,


Fig. 4. The gam $_{\text {crit }}$ value for different $q d p$


Fig. 5. Dependence of $d_{\max }\left(e_{00}\right)$ for principal stress directions: a) $q d p=0.8$ and b) $q d p=0.5$
the value of $d_{\text {max }}$ is approximately three times smaller than at high pressures and that is the evidence in favour of the pulsed nature of the fracturing. In order to achieve a high rate of fluid flow it is necessary to use more efficient pumps or special high-capacity hydropneumatic accumulators automatically switching on at time of fracture formation.

## Summary

1. The algorithm for calculating the trajectory of the synchronous longitudinal hydraulic fracturing carried out in parallel wells and research software based on this algorithm were developed.
2. The influence of coal rocks stress state to the maximum possible distance between wells providing fractures linkage was determined. Also it is emphasized the desirability of pulsed fracturing with high rates of fluid flow in to the growing crack.
3. The obtained results help to design hydraulic fracture treatments in coal measure rocks in order to solve the problem of underground methane production or intensification of beds degassing.

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## Численные исследования процесса

гидроразрыва угольного пЛаста

## для эффективной дегазации метана

A. В. Патутин,<br>П. А. Мартынюк, С. В. Сердюков<br>Институт горного дела CO PAH<br>Россия 630091, Новосибирск, Красный пр. 54


#### Abstract

При проведении горных работ необходима эффективная дегазация угольных пластов. В статье представлен алгоритм, использующийся для расчета траектории трещины, которая формируется в результате проведения операции гидроразрьва в нескольких параллельных скважинах. Результать численного анализа показывают, что направление распространения трещинызависит от приложенного кнейдавления и напряженного состояниямассива. Оиенено максимальное расстояние между скважинами гидроразрыва, при котором происходит их сбойка. Полученные результать могут быть использованы при проектировании гидроразрыва в угольных пластах с целью добычи метана либо для интенсификацุии дегазацции углепородного массива.


Ключевые слова: численное моделирование, дегазачия метана, управляемый гидроразрыв, метан угольных пластов.


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    * Corresponding author E-mail address: andrey.patutin@gmail.com

