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Boundary Morera Theorem for the Matrix Ball of the Third Type

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In the article we consider a boundary version of Morera's theorem for the matrix ball of the third type.

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¹⁰. We have the following result of Nagel and Rudin [1] which says that if f is a continuous function on the boundary of the unit ball in \mathbb{C}^n and the integral

$$\int_0^{2\pi} f(\psi(e^{i\varphi}, 0, \dots, 0)) e^{i\varphi} d\varphi = 0$$

for all (holomorphic) automorphisms ψ of the ball, the function f extends holomorphically into a ball. For the classical domains, the matrix ball of the first type, and the generalized upper half-plane the boundary analogs of the Morera theorem were obtained in [2–4].

²⁰. Let $Z = (Z_1, \dots, Z_n)$ be a vector composed from square matrices Z_j of order m over the field of complex numbers \mathbb{C} . We can assume that Z is an element of the space \mathbb{C}^{m^2n} . We introduce on this set of vectors a matrix ‘scalar’ product according to

$$\langle Z, W \rangle = Z_1 W_1^* + \dots + Z_n W_n^*,$$

where W_j^* is a conjugate transpose of the matrix W_j .

The set

$$B_{m,n}^{(1)} = \{(Z_1, \dots, Z_n) = Z \in \mathbb{C}^n [m \times m] : I - \langle Z, Z \rangle > 0\},$$

is called a matrix ball (of the first type); here $\langle Z, Z \rangle = Z_1 Z_1^* + Z_2 Z_2^* + \dots + Z_n Z_n^*$ is the ‘scalar’ product, I is the identity $[m \times m]$ -matrix, $Z_\nu^* = \overline{Z}'_\nu$ is the conjugate transpose of Z_ν , $\nu = 1, 2, \dots, n$, [5]. Here $I - \langle Z, Z \rangle > 0$ means that the Hermitian matrix $I - \langle Z, Z \rangle$ is positively defined, i.e. all its eigenvalues are positive.

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3⁰. We consider a matrix ball $B_{m,n}^{(3)}$ (of the third type) (see [6]:

$$B_{m,n}^{(3)} = \{(Z_1, \dots, Z_n) = Z \in \mathbb{C}^n [m \times m] : I + \langle Z, Z \rangle > 0, \quad Z'_\nu = -Z_\nu, \quad \nu = 1, \dots, n\}.$$

The skeleton (the Shilov boundary) of the matrix ball $B_{m,n}^{(3)}$ is denoted by $X_{m,n}^{(3)}$, i.e.

$$X_{m,n}^{(3)} = \{Z \in \mathbb{C}^n [m \times m] : I + \langle Z, Z \rangle = 0, \quad Z'_\nu = -Z_\nu, \quad \nu = 1, \dots, n\}.$$

We fix a point $\Lambda^0 \in X_{m,n}^{(3)}$ ($\Lambda^0 = (\Lambda_1^0, \dots, \Lambda_n^0)$) and consider the following embedding of a unit disc Δ in the domain $B_{m,n}^{(3)}$

$$\left\{ W \in \mathbb{C}^{m^2 n} : W_j = t\Lambda_j^0, \quad j = 1, \dots, n, \quad |t| < 1 \right\}. \quad (1)$$

The boundary T of the disc Δ by this embedding is mapped into a circle lying on $X_{m,n}^{(3)}$. If ψ is an arbitrary (holomorphic) automorphism of $B_{m,n}^{(3)}$, then the set of the form (1) under the action of the automorphism goes into some analytic disc with boundary in $X_{m,n}^{(3)}$.

Theorem 1. *If the function $f \in C(X_{m,n}^{(3)})$ satisfies the following equality*

$$\int_T f(\psi(t\Lambda^0)) dt = 0 \quad (2)$$

for all automorphisms ψ of the ball $B_{m,n}^{(3)}$, then f extends holomorphically in $B_{m,n}^{(3)}$ to a function F of class $C(\bar{B}_{m,n}^{(3)})$.

Proof. We parameterize the manifold $X_{m,n}^{(3)}$. For $Z \in X_{m,n}^{(3)}$ we put $Z = e^{i\varphi}U$ where $0 \leq \varphi \leq 2\pi$, and the element $u_{11}^{(1)}$ in the upper left corner of the U_1 is a positive number. A manifold of such matrices is denoted by X^+ . Note that not the whole set $X_{m,n}^{(3)}$ is parameterized in this way, but a set smaller than $X_{m,n}^{(3)}$, differing by a set of measure 0.

Lemma 1 ([5]). *The measure*

$$d\sigma = h(U) dt d\sigma^+(U), \quad U \in X^+,$$

where $h(U)$ is a smooth positive function, does not depend on t .

Lemma 1 shows that the measure $d\sigma$ can be written as

$$d\sigma = \frac{d\phi}{2\pi} d\sigma_1(U) = \frac{1}{2\pi i} \frac{dt}{t} d\sigma_1(U),$$

where $t = e^{i\phi}$, the measure σ_1 is positive on X^+ .

Multiplying equation (2) by $d\sigma_1$ and integrating over X^+ , we obtain from (2)

$$\int_{X_{m,n}^{(3)}} f(\psi(Z)) z_{ks}^l d\sigma(Z) = 0 \quad (3)$$

where z_{ks}^l are the components of the vector $Z = (Z_1, \dots, Z_n)$, $k, s = 1, \dots, m$, $l = 1, \dots, n$.

Consider an automorphism $\psi_{B_{m,n}^{(3)}}$ that maps an arbitrary point A from $B_{m,n}^{(3)}$ to 0 [6]. It is defined up to a generalized unitary transformation.

Then, substituting in the condition (3) instead of ψ an automorphism $\psi_{B_{m,n}^{(3)}}^{-1}$ and making the change of variables $W = \psi_{B_{m,n}^{(3)}}^{-1}(Z)$, we obtain

$$\int_{X_{m,n}^{(3)}} f(W) \psi_{ks}^{A,l}(W) d\sigma(\psi_A(W)) = 0, \quad (4)$$

where $\psi_{ks}^{A,l}$ are the components of the automorphism $\psi_{B_{m,n}^{(3)}}$. □

Corollary 1 ([7]). *For any continuous function f defined on the skeleton $X_{m,n}^{(3)}$ the Poisson transformation $F = P[f]$ is a real-analytic function in $\bar{B}_{m,n}^{(3)} \setminus X_{m,n}^{(3)}$ and continuous on $\bar{B}_{m,n}^{(3)}$, and $F = f$ on $X_{m,n}^{(3)}$.*

Corollary 1 shows that $d\sigma(\psi_A(W)) = P(A, W)d\sigma((W))$, where $P(A, W)$ is an invariant Poisson kernel of the domain $B_{m,n}^{(3)}$.

Therefore, from the condition (3) we obtain

$$\int_{X_{m,n}^{(3)}} f(W)\psi_{ks}^{A,l}(W)P(A, W)d\sigma((W)) = 0 \tag{5}$$

for all the points A from $B_{m,n}^{(3)}$ and for all $k, s = 1, \dots, m, l = 1, \dots, n$.

Thus, taking into account Corollary 2 on the properties of the Poisson integral [7] of continuous functions, Theorem 1 follows from the following assertion.

Theorem 2. *If the function $f \in C(X_{m,n}^{(3)})$ and equation (5) holds for all automorphisms $\psi_{B_{m,n}^{(3)}}$ of the domain $B_{m,n}^{(3)}$ transforming a point A from $B_{m,n}^{(3)}$ to 0 and for all $k, s = 1, \dots, m, l = 1, \dots, n$, then the function is the radial boundary value of some function $F \in \sigma(B_{m,n}^{(3)})$.*

Proof. The invariant Poisson kernel for the domain $B_{m,n}^{(3)}$ has the following form (see [7]) for even m

$$\begin{aligned} P(A, W) &= \left[\frac{(\det(I^{(m)} + \langle A, A \rangle))}{(\det(I^{(m)} + \langle A, W \rangle))^2} \right]^{\frac{(m-1)n}{2}} = \left[\frac{(\det(I^{(m)} + A_1\bar{A}_1 + \dots + A_n\bar{A}_n))}{(\det(I^{(m)} + A_1\bar{W}_1 + \dots + A_n\bar{W}_n))^2} \right]^{\frac{(m-1)n}{2}} = \\ &= \frac{(\det(I^{(m)} + A_1\bar{A}_1 + \dots + A_n\bar{A}_n))^{\frac{(m-1)n}{2}}}{(\det(I^{(m)} + A_1\bar{W}_1 + \dots + A_n\bar{W}_n))^{\frac{(m-1)n}{2}} (\det(I^{(m)} + W_1\bar{A}_1 + \dots + W_n\bar{A}_n))^{\frac{(m-1)n}{2}}}, \end{aligned}$$

and for odd m

$$\begin{aligned} P(A, W) &= \left[\frac{(\det(I^{(m)} + \langle A, A \rangle))}{(\det(I^{(m)} + \langle A, W \rangle))^2} \right]^{\frac{m}{2}} = \left[\frac{(\det(I^{(m)} + A_1\bar{A}_1 + \dots + A_n\bar{A}_n))}{(\det(I^{(m)} + A_1\bar{W}_1 + \dots + A_n\bar{W}_n))^2} \right]^{\frac{m}{2}} = \\ &= \frac{(\det(I^{(m)} + A_1\bar{A}_1 + \dots + A_n\bar{A}_n))^{\frac{m}{2}}}{(\det(I^{(m)} + A_1\bar{W}_1 + \dots + A_n\bar{W}_n))^{\frac{m}{2}} (\det(I^{(m)} + W_1\bar{A}_1 + \dots + W_n\bar{A}_n))^{\frac{m}{2}}}. \end{aligned}$$

Let

$$\begin{aligned} A &= (A_1, \dots, A_n) = \\ &= (0, a_{12}^1, \dots, a_{1m}^1; a_{m1}^1, \dots, a_{m(m-1)}^1, 0; \dots; 0, a_{12}^n, \dots, a_{1m}^n; \dots; a_{m1}^n, \dots, a_{m(m-1)}^n, 0) = \\ &= (\|a_{sp}^1, \dots, a_{sp}^n\|), \\ W &= (W_1, \dots, W_n) = \\ &= (0, w_{12}^1, \dots, w_{1m}^1; w_{m1}^1, \dots, w_{m(m-1)}^1, 0; \dots; 0, w_{12}^n, \dots, w_{1m}^n; \dots; w_{m1}^n, \dots, w_{m(m-1)}^n, 0) = \\ &= (\|w_{sp}^1, \dots, w_{sp}^n\|), \end{aligned}$$

where $\|a_{sp}^l\| = \|-a_{ps}^l\|$, $\|w_{sp}^l\| = \|-w_{ps}^l\|$, $(s, p = 1, \dots, m), l = 1, \dots, n$.

We find the expression

$$\sum_{s,p=1}^m \sum_{l=1}^n \bar{v}_{sp}^l \frac{\partial P(A, W)}{\partial \bar{a}_{sp}^1}. \tag{6}$$

Denote

$$I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n = \|\alpha_{qj}\| \quad (q, j = 1, \dots, m),$$

where $\alpha_{qj} = \delta_{qj} + \sum_{k=1}^m \sum_{l=1}^n w_{qk}^l \bar{a}_{jk}^l$, $a_{sp}^l = -a_{ps}^l$, $w_{sp}^l = -w_{ps}^l$, $q, j = 1, \dots, m$, and δ_{qj} is the Kronecker delta.

Using the usual rule for differentiating a determinant for any $s=1, \dots, m$ we obtain

$$\sum_{p=1}^m \sum_{l=1}^n \bar{a}_{sp}^l \frac{\partial \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)}{\partial \bar{a}_{sp}^l} =$$

$$= \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n) - \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)[s, s],$$

where $\det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)[s, s]$ denotes the algebraic complement to the element α_{ss} in the matrix $\det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)$.

Then

$$\sum_{s,p=1}^m \sum_{l=1}^n \bar{a}_{sp}^l \frac{\partial \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)}{\partial \bar{a}_{sp}^l} =$$

$$= m \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n) - \sum_{s=1}^m \det(I^{(m)} + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)[s, s].$$

Similarly,

$$\sum_{s,p=1}^m \sum_{l=1}^n \bar{a}_{sp}^l \frac{\partial \det(I^{(m)} + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)}{\partial \bar{a}_{sp}^l} =$$

$$= m \det(I^{(m)} + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n) - \sum_{s=1}^m \det(I^{(m)} + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)[s, s].$$

Hence for even m we have the following equality

$$\begin{aligned} & \frac{m(m-1)n}{2} P(A, W) \cdot \left[\frac{\sum_{s=1}^m \det(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)[s, s]}{\det(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)} - \right. \\ & \quad \left. - \frac{\sum_{s=1}^m \det(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)[s, s]}{\det(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)} \right] = \\ & = \frac{m(m-1)n}{2} P(A, W) [Sp(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)^{-1} - Sp(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)^{-1}]. \quad (7) \end{aligned}$$

for odd m the following equality

$$\begin{aligned} & \frac{m(m+1)n}{2} P(A, W) \cdot \left[\frac{\sum_{s=1}^m \det(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)[s, s]}{\det(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)} - \right. \\ & \quad \left. - \frac{\sum_{s=1}^m \det(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)[s, s]}{\det(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)} \right] = \\ & = \frac{m(m+1)n}{2} P(A, W) [Sp(I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n)^{-1} - Sp(I + A_1 \bar{A}_1 + \dots + A_n \bar{A}_n)^{-1}]. \quad (7') \end{aligned}$$

Here SpW denotes the trace of W .

The mapping of the form [6]

$$\psi_A(W) = \bar{Q}^{-1} \left((I + W_1 \bar{A}_1 + \dots + W_n \bar{A}_n) \right)^{-1} \sum_{s=1}^n (W_s - A_s) Q_{sk}, \quad k = 1, \dots, n,$$

transforming a point A to the origin, is an automorphism of the matrix ball $B_{m,n}^{(3)}$, where Q is the block matrix $\overline{Q}(I + A_1\overline{A}_1 + \dots + A_n\overline{A}_n)Q' = I$.

If the condition (5) holds for the components of the map $\psi_A(W)$, the same condition holds for the components of the map

$$\psi_A(W) = \left(I^{(m)} + A_1\overline{A}_1 + \dots + A_n\overline{A}_n \right)^{-1} \left(I^{(m)} + W_1\overline{A}_1 + \dots + W_n\overline{A}_n \right)^{-1} \sum_{s=1}^n (W_s - A_s),$$

because the matrices Q and $I^{(m)} + W_1\overline{A}_1 + \dots + W_n\overline{A}_n$ are non-degenerate and depend only on A .

Then from (5) we get

$$\int_{X_{m,n}^{(3)}} f(W)\psi_{ks}^{A,l}(W)P(A,W)d\sigma(W) = 0,$$

where $\psi_{ks}^{A,l}(W)$ are components of the map $\psi_A(W)$, $(s, p = 1, \dots, m)$, $\nu = 1, \dots, n$. Consider the sum

$$\sum_{s,p=1}^m \sum_{l=1}^n \overline{a}_{sp}^l \psi_{sp}^{A,l}.$$

Obviously, this expression is equal to $Sp \langle \psi_A(W), A \rangle$, as [8–10]

$$\begin{aligned} \sum_{s,p=1}^m \sum_{l=1}^n \overline{a}_{sp}^l \psi_{sp}^{A,l} &= Sp \left[(I^{(m)} + A_1\overline{A}_1 + \dots + A_n\overline{A}_n)^{-1} (I^{(m)} + W_1\overline{A}_1 + \dots + W_n\overline{A}_n)^{-1} \times \right. \\ &\quad \left. \times (A_1\overline{A}_1 + \dots + A_n\overline{A}_n - W_1\overline{A}_1 - \dots - W_n\overline{A}_n) \right] = \\ &= Sp \left[(I^{(m)} + A_1\overline{A}_1 + \dots + A_n\overline{A}_n)^{-1} (I^{(m)} + W_1\overline{A}_1 + \dots + W_n\overline{A}_n)^{-1} \times \right. \\ &\quad \left. \times ((I + A_1\overline{A}_1 + \dots + A_n\overline{A}_n) - (I + W_1\overline{A}_1 + \dots + W_n\overline{A}_n)) \right] = \\ &= Sp \left[(I^{(m)} + W_1\overline{A}_1 + \dots + W_n\overline{A}_n)^{-1} - (I^{(m)} + A_1\overline{A}_1 + \dots + A_n\overline{A}_n)^{-1} \right]. \end{aligned} \tag{8}$$

Comparing formulas (7) and (8), from the hypothesis of the theorem we obtain

$$\sum_{s,p=1}^m \sum_{l=1}^n \overline{a}_{sp}^l \frac{\partial F(A)}{\partial \overline{b}_{sp}^l} = 0, \tag{9}$$

where $F(A) = \int_{X_{m,n}^{(3)}} f(W)P(A,W)d\sigma(W)$ is the Poisson integral of the function f . □

4⁰. The proof of this theorem shows that it remains valid if the condition (5) holds only for automorphisms $\psi_{B_{m,n}^{(3)}}$, for which the point A lies in an open set $V \subset B_{m,n}^{(3)}$. As Theorem 1, Theorem 2 can be generalized.

Theorem 3. *Let the function $f \in C(X_{m,n}^{(3)})$ and the condition (2) holds for all automorphisms ψ that transform the origin to a point of some open set $V \subset B_{m,n}^{(3)}$. Then f holomorphically extends in the domain $B_{m,n}^{(3)}$ to a function $F \in \sigma(\overline{B}_{m,n}^{(3)})$.*

5⁰. Let Δ_ψ be an analytic disc

$$\Delta_\psi = \{Z : Z = \psi(t\Lambda^0), |t| < 1\},$$

where Λ_r^0 is a fixed point of the skeleton $X_{m,n}^{(3)}$, and ψ is an automorphism of the domain $B_{m,n}^{(3)}$. Then the boundary T_ψ of the analytic disc lies on $X_{m,n}^{(3)}$, since the automorphism maps points of the skeleton to the points of the skeleton.

From the Morera theorems we obviously get a corollary on functions with one-dimensional holomorphic extension property along analytic discs.

Corollary 3. *If the function $f \in C(X_{m,n}^{(3)})$ extends holomorphically (in t) in analytic discs Δ_ψ for all automorphisms ψ (or for all automorphisms ψ that transform the origin to a point of some fixed open set $V \subset B_{m,n}^{(3)}$), then the function f extends holomorphically in $B_{m,n}^{(3)}$.*

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Граничная теорема Морера для матричного шара третьего типа

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В этой статье рассматривается граничный вариант теоремы Мореры для матричного шара третьего типа.

Ключевые слова: матричный шар первого типа, матричный шар третьего типа, ядро Пуассона, теорема Морера.