

# Residue Integrals and Waring's Formulas for Algebraic or Even Transcendental Systems

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## Abstract

The present article is focused on the study of a special class of systems of nonlinear transcendental equations for which classical algebraic and symbolic methods are inapplicable. For the purpose of study of such systems we develop a method for computing residue integrals with integration over certain cycles. We describe conditions under which the mentioned residue integrals coincide with power sums of the inverses to the roots of a system of equations (i.e., multidimensional Waring's formulas). Based on this we develop an algorithm that computes such power sums without computing the roots. As an application of the suggested method, we consider a problem of finding sums of multi-variable number series.

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## 1 Introduction

The problem of elimination of unknowns from systems of nonlinear algebraic equations is a classical algebraic problem. Its solution based on the notion of resultant was developed in works of Sylvester and Bézout. This method was described in detail in the classical Van der Waerden's monograph [25]. In the middle of the 20th century, B. Buchberger suggested a new elimination method based on the notion of a Gröbner basis. Nowadays it is one of the main elimination methods in polynomial computer algebra (see, e.g., [1, 4]).

In the 1970s in [2] L. A. Aizenberg proposed a new elimination method based on the multidimensional residue theory, namely on the formulas of multidimensional logarithmic residue and Grothendieck residue. The basic idea of the method was to find certain residue integrals

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connected to the power sums of roots of a given system of equations without finding the roots themselves. (The formulas for computing power sums may vary depending on the given system of equations.) Then, using the classical recurrent Newton formulas, one can construct a polynomial whose roots coincide with the first coordinates of the roots of the given system with the same multiplicity (i.e., resultant). This method does not increase the multiplicity of roots in comparison with the classical method (see, e.g., [25]). Its further developments were implemented in [3], [24], and [5].

In applied problems of chemical kinetics systems of transcendental equations, namely, systems consisting of exponential polynomials [6, 8] (Zeldovich–Semenov model, etc.) arise as well. However, the elimination method developed in [3, 5, 24] cannot be applied to this kind of systems. One of the obstacles is the fact that the set of roots of a system of  $n$  transcendental equations in  $n$  variables is, in general, infinite. Moreover, multi-Newton sums (with powers in  $\mathbb{N}^n$ ) of the roots of such systems lead usually to divergent series. At the same time, the multidimensional logarithmic residue and Grothendieck residue formulas are not applicable to the residue integrals that arise in such kind of systems which means that one is unable to calculate power sums of the roots. Therefore, the known methods have to be modified significantly in order to be applied to such systems. In particular, one has to be able to compute power sums of the inverses to the roots (without finding the roots themselves). Then, using the obtained formulas together with analogs of recurrent Newton formulas and Waring’s formulas for entire functions of a complex variable (see [5, Ch. 1]), one can construct resultant, which is also an entire function. But nevertheless, the formulas for finding power sums are still the main component of the method.

Classical Waring’s formulas express power sums of the roots of a polynomial in terms of its coefficients (see, e.g., [25]). Multidimensional analogs of Waring’s formulas for certain types of algebraic systems were developed in [10].

In the works [7, 11, 13–18] simple enough classes of systems of equations containing entire or meromorphic functions were considered. An algorithm that computes the residue integrals and applies to them the recurrent Newton formulas was given in [12]. In [9] the developed methods were applied to study of a system (consisting of exponential polynomials) that arises in Zeldovich–Semenov model.

We now present a more precise review of the known results. In [18] the authors considered the system of functions:

$$f_1(z), \dots, f_n(z),$$

where  $z = (z_1, \dots, z_n)$ . Each  $f_j(z)$  is analytic in the neighborhood of  $0 \in \mathbb{C}^n$  and is defined by

$$f_j(z) = z^{\beta^j} + Q_j(z), \quad j = 1, \dots, n,$$

where  $\beta^j = (\beta_1^j, \dots, \beta_n^j)$  is a multi-index with integer nonnegative coordinates,  $z^{\beta^j} = z_1^{\beta_1^j} \dots z_n^{\beta_n^j}$ , and  $\|\beta^j\| = \beta_1^j + \dots + \beta_n^j = k_j$ ,  $j = 1, \dots, n$ . Functions  $Q_j$  are expanded in a neighborhood of origin into an absolutely and uniformly converging Taylor series of the form

$$Q_j(z) = \sum_{\|\alpha\| > k_j} a_\alpha^j z^\alpha,$$

where  $\alpha = (\alpha_1, \dots, \alpha_n)$ ,  $\alpha_j \geq 0$ ,  $\alpha_j \in \mathbb{Z}$ , and  $z^\alpha = z_1^{\alpha_1} \dots z_n^{\alpha_n}$ .

The formulas for computing residue integrals

$$J_\beta = \frac{1}{(2\pi i)^n} \int_{\gamma(r)} \frac{1}{z^{\beta+U}} \cdot \frac{df}{f}$$

(here  $i = \sqrt{-1}$ ) in terms of the coefficients of  $Q_j(z)$  were obtained. Here  $\gamma(r) = \{z = (z_1, \dots, z_n) : |z_j| = r_j, j = 1, \dots, n\}$  and  $U = (1, \dots, 1)$  is the unit vector.

Multidimensional Newton formulas for such systems were obtained in [11] and [12].

A class of systems containing the functions

$$f_j(z) = (z^{\beta_j} + Q_j(z))e^{P_j}, \quad j = 1, \dots, n. \quad (1)$$

was considered in [15] and [13]. A method for finding residue integrals for such systems was given in [13].

In the present work we compute residue integrals for a specific kind of systems of  $n$  transcendental equations, and deduce from this computation (provided such series converge) the values of the sums of series (with powers in  $(-\mathbb{N})^n$ ) consisting of the roots of such systems which do not belong to coordinate subspaces. In other words, we generalize the statements from [7, 11, 13, 15, 18] to a wider class of systems of transcendental equations, where instead of the monomials  $z^{\beta_j}$  in (1) we consider products of linear functions. Our objectives are to obtain formulas for computing residue integrals, to study the connection between residue integrals and power sums of the inverses to the roots (Waring's formulas), and to introduce a scheme for elimination of unknowns from the considered class of systems.

## 2 Calculation of residue integrals

In this section, we introduce the class of systems of transcendental equations that will be considered in this work. A. Tsikh considered its algebraic analog in [23] (see also [5, Theorems 8.5, 8.6]) and studied the number of its common roots in  $(\mathbb{P}^1(\mathbb{C}))^n$ . Theorem 2 shows that for any such system the residue integral  $J_\gamma(t)$  (where  $t > 0$  is sufficiently small) can be computed by means of converging series of Taylor coefficients of the functions contained in the initial system.

For  $z = (z_1, \dots, z_n) \in \mathbb{C}^n$  consider a system of functions

$$\begin{cases} f_1(z) = q_1(z) + Q_1(z), \\ \dots \\ f_n(z) = q_n(z) + Q_n(z), \end{cases} \quad (2)$$

where  $Q_j(z)$  are entire functions and

$$q_j(z_1, \dots, z_n) = (1 - a_{j1}z_1)^{m_{j1}} \dots (1 - a_{jn}z_n)^{m_{jn}} \quad (3)$$

for  $j = 1, \dots, n$ . Here  $m_{jk}$  are positive integers and  $a_{jk}$  are complex numbers, such that  $a_{jk} \neq a_{sk}$ ,  $j \neq k$ .

Let  $J = (j_1, \dots, j_n)$  be a multi-index where  $(j_1 \dots j_n)$  is a permutation of  $(1 \dots n)$ . Then by  $a_J$  we denote the vector  $(a_{1j_1}, \dots, a_{nj_n})$ . For each  $i$  we define a function

$$h_j(z) = \begin{cases} q_j(z), & \text{if } a_{jk} \neq 0 \text{ for each } k; \\ q_j(z) \cdot \frac{1}{z_{k_1}} \cdot \dots \cdot \frac{1}{z_{k_s}}, & \text{if } a_{jk_1} = \dots = a_{jk_s} = 0. \end{cases}$$

The system

$$h_i(z) = 0, \quad i = 1, \dots, n \quad (4)$$

has  $n!$  isolated roots (computed without multiplicities) in  $(\mathbb{P}^1(\mathbb{C}))^n$ . Since  $\mathbb{P}^1(\mathbb{C})$  is a compactification of the complex plane  $\mathbb{C}$ , then  $(\mathbb{P}^1(\mathbb{C}))^n$  is one of the known compactifications of  $\mathbb{C}^n$ . The roots of (4) are

$$\tilde{a}_J = \begin{cases} (1/a_{1j_1}, \dots, 1/a_{nj_n}), & \text{if } a_{kj_k} \neq 0 \text{ for each } k = 1, \dots, n, \\ (1/a_{1j_1}, \dots, \infty_{[i_1]}, \dots, \infty_{[i_k]}, \dots, 1/a_{nj_n}), & \text{if } a_{i_1j_{i_1}} = \dots = a_{i_kj_{i_k}} = 0, \end{cases}$$

where  $k, j = 1, \dots, n$ , and  $J = (j_1, \dots, j_n)$ . Note that we write  $\infty$  (as a point in  $\mathbb{P}^1(\mathbb{C})$ ) in  $\tilde{a}_J$  whenever  $a_{kj_k} = 0$ .

By  $\Gamma_h$  we denote the cycle

$$\Gamma_h = \{z \in \mathbb{C}^n : |h_j(z)| = r_j, r_j > 0, j = 1, \dots, n\}. \quad (5)$$

Now we define the cycle  $\Gamma_{h, \tilde{a}_J}$  by

$$\begin{cases} |l_1| = r_1, \\ \dots \\ |l_n| = r_n, \end{cases} \quad \text{where} \quad \begin{cases} l_k = 1 - a_{kj_k} z_k, & \text{if } a_{kj_k} \neq 0, \\ l_k = 1/z_k, & \text{if } a_{kj_k} = 0. \end{cases} \quad (6)$$

**Lemma 1.** *For sufficiently small  $r_i$  a global cycle  $\Gamma_h$  defined by (5) has connected components (local cycles) in the neighborhoods of the roots  $a_J$ . Moreover,  $\Gamma_h$  is homologous to the sum of the local cycles  $\Gamma_{h, \tilde{a}_J}$ .*

*Proof.* Consider the global cycle  $\Gamma_h$  defined by

$$\begin{cases} |h_1| = r_1, \\ \dots \\ |h_n| = r_n. \end{cases}$$

If  $a_{kj_k} \neq 0$  for any  $k = 1, \dots, n$  in a neighborhood of  $a_J$ , then  $\Gamma_h$  is homotopic to the cycle  $\Gamma_{q, \tilde{a}_J}$  defined by (6) with the homotopy defined by

$$\begin{cases} |1 - ta_{11}z_1|^{m_{11}} \dots |1 - a_{1j_1}z_{j_1}|^{m_{1j_1}} \dots |1 - ta_{1n}z_n|^{m_{1n}} = r_1, \\ \dots \\ |1 - ta_{n1}z_1|^{m_{n1}} \dots |1 - a_{nj_n}z_{j_n}|^{m_{nj_n}} \dots |1 - ta_{nn}z_n|^{m_{nn}} = r_n, \end{cases} \quad (7)$$

where  $t \in [0, 1]$ . For  $t = 1$  we obtain  $\Gamma_h$ , and for  $t = 0$  we obtain  $\Gamma_{h, \tilde{a}_J}$ .

Now we consider  $\Gamma_h$  in the neighborhood of  $a_J$  where  $a_{i_1j_{i_1}} = \dots = a_{i_kj_{i_k}} = 0$ . Then in such neighborhood  $\Gamma_h$  is homotopic to the cycle  $\Gamma_{h, \tilde{a}_J}$  defined by (6), and the homotopy is defined similarly to (7) where for each  $a_{i_kj_{i_k}} = 0$  the corresponding term  $1 - a_{i_kj_{i_k}} z_{j_{i_k}}$  is replaced with  $1/z_{i_k}$ .  $\square$

For

$$F_j(z, t) = q_j(z) + t \cdot Q_j(z), \quad j = 1, \dots, n \quad (8)$$

consider the system of equations  $F_j(z, t) = 0$  which depends on a real parameter  $t \geq 0$ .

Let  $r_1 > 0, \dots, r_n > 0$  be fixed real numbers. Compactness of the cycles  $\Gamma_h$  defined by (5) yields the fact that for sufficiently small  $t > 0$ , the inequalities

$$|q_j(z)| > |t \cdot Q_j(z)|, \quad j = 1, \dots, n$$

hold on  $\Gamma_h$ .

By  $J_\gamma(t)$  we denote the integral

$$J_\gamma(t) = \frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z^{\gamma+I}} \cdot \frac{d_z F}{F} = \frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z_1^{\gamma_1+1} \dots z_n^{\gamma_n+1}} \cdot \frac{d_z F_1}{F_1} \wedge \dots \wedge \frac{d_z F_n}{F_n}, \quad (9)$$

where  $\gamma = (\gamma_1, \dots, \gamma_n)$  is a multi-index and  $I = (1, \dots, 1)$ . This integral we call the residue integral in accordance with the paper [21].

We now introduce the following notations used in the theorem below and in some of the further statements.

Denote by  $\Delta = \Delta(t)$  the Jacobian of the system  $F_1(z, t), \dots, F_n(z, t)$  with respect to  $z_1, \dots, z_n$ :

$$\Delta = \det \begin{pmatrix} \frac{\partial F_1}{\partial z_1} & \dots & \frac{\partial F_1}{\partial z_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_n}{\partial z_1} & \dots & \frac{\partial F_n}{\partial z_n} \end{pmatrix}$$

Recall that  $(j_1 \dots j_n)$  is a permutation of  $(1 \dots n)$ . By  $(-1)^{s(J)}$  we denote the sign of  $J$ .

Let  $\alpha = (\alpha_1, \dots, \alpha_n)$  be a multi-index of length  $n$ . By  $q^{\alpha+I}(J)$  we denote the quantity

$$q_1^{\alpha_1+1}[j_1] \cdot \dots \cdot q_n^{\alpha_n+1}[j_n],$$

where  $q_s[j_s]$  is the product  $(1 - a_{j_1 z_1})^{m_{j_1}} \cdot \dots \cdot (1 - a_{j_n z_n})^{m_{j_n}}$  with the term  $(1 - a_{s j_s} z_s)^{m_{s j_s}}$  omitted:

$$q_s[j_s] = \prod_{\substack{1 \leq k \leq n \\ k \neq s}} (1 - a_{j_k z_k})^{m_{j_k}}.$$

By  $\beta(\alpha, J)$  we denote the vector

$$\beta(\alpha, J) = (m_{1 j_1}(\alpha_{j_1} + 1) - 1, \dots, m_{n j_n}(\alpha_{j_n} + 1) - 1),$$

and

$$\beta(\alpha, J)! = \prod_p (m_{p j_p}(\alpha_{j_p} + 1) - 1)!$$

Finally,  $a_J^{\beta+I}$  denotes  $a_{1 j_1}^{m_{1 j_1}(\alpha_{j_1}+1)} \cdot \dots \cdot a_{n j_n}^{m_{n j_n}(\alpha_{j_n}+1)}$ , and

$$\frac{\partial^{|\beta(\alpha, J)|}}{\partial z^{\beta(\alpha, J)}} = \frac{\partial^{m_{1 j_1}(\alpha_{j_1}+1)-1+\dots+m_{n j_n}(\alpha_{j_n}+1)-1}}{\partial z_1^{m_{1 j_1}(\alpha_{j_1}+1)-1} \dots \partial z_n^{m_{n j_n}(\alpha_{j_n}+1)-1}}$$

is a differentiation operator.

**Theorem 2.** *Under the assumptions made for the functions  $F_i$  defined by (8), the following formulas for  $J_\gamma(t)$  as convergent (for sufficiently small  $t$ ) series are valid:*

$$J_\gamma(t) = \sum_J' \sum_\alpha (-t)^{|\alpha|+|\beta(\alpha, J)|+n} \frac{(-1)^{s(J)}}{\beta(\alpha, J)! \cdot a_J^{\beta+I}} \times \frac{\partial^{|\beta(\alpha, J)|}}{\partial z^{\beta(\alpha, J)}} \left[ \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdot \dots \cdot z_n^{\gamma_n+1}} \cdot \frac{Q^\alpha}{q^{\alpha+I}(J)} \right]_{z=\bar{a}_J},$$

where  $\sum_J'$  means that the summation is performed over all multi-indices  $J$  such that  $a_J$  have no zero components.

*Proof.* We have

$$\begin{aligned}
J_\gamma(t) &= \frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z^{\gamma+I}} \cdot \frac{dF}{F} \\
&= \frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{dF_1}{F_1} \wedge \cdots \wedge \frac{dF_n}{F_n} \\
&= \frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z^{\gamma+I}} \cdot \frac{\Delta dz}{F},
\end{aligned}$$

where  $dz = dz_1 \wedge \cdots \wedge dz_n$ , and  $F = F_1 \cdots F_n$ .

Applying a formula for the sum of a geometric series, we get

$$\begin{aligned}
&\frac{1}{(2\pi i)^n} \int_{\Gamma_h} \frac{1}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{\Delta dz}{F_1 \cdots F_n} \\
&= \frac{1}{(2\pi i)^n} \sum_{\|\alpha\| \geq 0} (-t)^{\|\alpha\|} \int_{\Gamma_h} \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{Q_1^{\alpha_1} \cdots Q_n^{\alpha_n}}{q_1^{\alpha_1+1} \cdots q_n^{\alpha_n+1}} dz \\
&= \frac{1}{(2\pi i)^n} \sum_J \sum_{\|\alpha\| \geq 0} (-t)^{\|\alpha\|} \int_{\Gamma_{\Gamma_h, \bar{a}_J}} \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{Q_1^{\alpha_1} \cdots Q_n^{\alpha_n}}{q_1^{\alpha_1+1} \cdots q_n^{\alpha_n+1}} dz \\
&= \frac{1}{(2\pi i)^n} \sum_J' \sum_{\|\alpha\| \geq 0} (-t)^{\|\alpha\|} \int_{\Gamma_{\Gamma_h, \bar{a}_J}} \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{Q_1^{\alpha_1} \cdots Q_n^{\alpha_n}}{q_1^{\alpha_1+1} \cdots q_n^{\alpha_n+1}} dz \\
&= \frac{1}{(2\pi i)^n} \sum_J' (-1)^{s(J)} \sum_{\|\alpha\| \geq 0} (-t)^{\|\alpha\|} \times \\
&\quad \times \int_{\Gamma_{h, \bar{a}_J}} \frac{\Delta(t)}{z^{\gamma+I}} \cdot \frac{Q^\alpha dz}{q_1^{\alpha_1+1} [j_1] \cdots q_n^{\alpha_n+1} [j_n] (1 - a_{1j_1} z_{j_1})^{(\alpha_1+1)m_{1j_1}} \cdots (1 - a_{nj_n} z_{j_n})^{(\alpha_n+1)m_{nj_n}}},
\end{aligned}$$

and finally we obtain that  $J_\gamma(t)$  is equal to

$$\sum_J' \sum_\alpha (-t)^{\|\alpha\| + \|\beta\| + n} \frac{(-1)^{s(J)}}{\beta(\alpha, J)! \cdot a_J^{\beta+I}} \cdot \frac{\partial^{\|\beta(\alpha, J)\|}}{\partial z^{\beta(\alpha, J)}} \left[ \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{Q^\alpha}{q^{\alpha+I}(J)} \right]_{z=\bar{a}_J}.$$

The resulting series converges for sufficiently small  $t$ . □

### 3 Residue integrals and Waring's formulas for algebraic systems

In this section we establish a correspondence between the residue integrals and the power sums of the inverses to the roots (Waring's formulas). First we shrink the class of systems for which the sums in Theorem 2 are finite. Then, applying the transformations  $z_j = \frac{1}{w_j}$ ,  $j = 1, \dots, n$ , and

Lemma 4 by A. Tsikh we rewrite the residue integrals  $J_\gamma(t)$  in the new variables  $w$  (Lemma 3). Further, Lemma 5 shows that  $J_\gamma(t)$  can be expressed by a finite number of Taylor coefficients of the considered functions. Theorem 7 shows (by means of Lemma 6) that the residue integral  $J_\gamma(t)$  equals (up to a sign) to the power sums of the inverses to the roots. The main result of the paper, Theorem 8, shows that the statement of Theorem 7 is true not only for sufficiently small  $t > 0$  but also for  $t = 1$ . (Note that Theorems 8 and 9 allow one find power sums of the inverses to the roots of the systems without finding the roots.) As a conclusion of the section we present an elimination method for the considered systems.

Suppose

$$Q_j(z) = z_1 \cdot \dots \cdot z_n \sum_{|\alpha| \geq 0} C_\alpha^j z^\alpha \quad j = 1, \dots, n, \quad (10)$$

where  $\alpha$  is a multi-index,  $z^\alpha = z_1^{\alpha_1} \dots z_n^{\alpha_n}$ , and  $\deg_{z_k} Q_j \leq m_{jk}$ ,  $j, k = 1, \dots, n$  for all non-zero  $a_{jk}$ . If  $a_{jk} = 0$  then no restriction on  $\deg_{z_k} Q_j$  is needed.

Assuming that all  $w_j \neq 0$ , we substitute  $z_j = \frac{1}{w_j}$ ,  $j = 1, \dots, n$  in the functions

$$F_j(z, t) = (q_j(z) + t \cdot Q_j(z)), \quad j = 1, \dots, n.$$

Consequently, for  $j = 1, \dots, n$ , we get

$$\begin{aligned} F_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}, t\right) &= q_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}\right) + t \cdot Q_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}\right) \\ &= \left(1 - a_{j1} \frac{1}{w_1}\right)^{m_{j1}} \dots \left(1 - a_{jn} \frac{1}{w_n}\right)^{m_{jn}} + t \cdot Q_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}\right) \\ &= \left(\frac{1}{w_1}\right)^{m_{j1}} \dots \left(\frac{1}{w_n}\right)^{m_{jn}} \cdot (w_1 - a_{j1})^{m_{j1}} \dots (w_n - a_{jn})^{m_{jn}} + t \cdot Q_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}\right). \end{aligned}$$

And finally we arrive at

$$F_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}, t\right) = \left(\frac{1}{w_1}\right)^{m_{j1}} \dots \left(\frac{1}{w_n}\right)^{m_{jn}} \cdot \left(\tilde{q}_j(w) + t \cdot \tilde{Q}_j(w)\right), \quad (11)$$

where  $\tilde{q}_j$  are the functions

$$\tilde{q}_j = (w_1 - a_{j1})^{m_{j1}} \dots (w_n - a_{jn})^{m_{jn}},$$

$\tilde{Q}_j$  are the polynomials

$$\tilde{Q}_j = w_1^{m_{j1}} \dots w_n^{m_{jn}} \cdot Q_j\left(\frac{1}{w_1}, \dots, \frac{1}{w_n}\right),$$

and

$$\tilde{F}_j = \tilde{F}_j(w, t) = \tilde{q}_j(w) + t \cdot \tilde{Q}_j(w), \quad j = 1, \dots, n. \quad (12)$$

From (10) we obtain

$$\deg_{w_j} \tilde{Q}_j < m_{jk}, \quad j, k = 1, \dots, n.$$

Note that in the above calculations it is not important whether  $a_{jk}$  vanish or not. Indeed, suppose that in  $F_j(z, t) = q_j(z) + t \cdot Q_j(z)$ ,  $j = 1, \dots, n$ , some  $a_{jk} = 0$ . If, for instance,  $a_{11} = 0$ , then after the substitution  $z_j = \frac{1}{w_j}$ ,  $j = 1, \dots, n$ , the function  $F_1$  takes the form

$$F_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n}, t \right) = q_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right) + t \cdot Q_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right),$$

where

$$\begin{aligned} q_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right) &= \left( 1 - a_{12} \frac{1}{w_2} \right)^{m_{12}} \cdot \dots \cdot \left( 1 - a_{1n} \frac{1}{w_n} \right)^{m_{1n}} \\ &= \left( \frac{1}{w_1} \right)^{\deg_{w_1} Q_1} \cdot \left( \frac{1}{w_2} \right)^{m_{12}} \cdot \dots \cdot \left( \frac{1}{w_n} \right)^{m_{1n}} \\ &\quad \times w_1^{\deg_{w_1} Q_1} \cdot (w_2 - a_{12})^{m_{12}} \cdot \dots \cdot (w_n - a_{1n})^{m_{1n}}. \end{aligned}$$

Consequently

$$F_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n}, t \right) = \left( \frac{1}{w_1} \right)^{\deg_{w_1} Q_1} \cdot \dots \cdot \left( \frac{1}{w_n} \right)^{m_{1n}} \cdot \left( \tilde{q}_1(w) + t \cdot \tilde{Q}_1(w) \right),$$

where

$$\tilde{q}_1 = (w_1)^{\deg_{w_1} Q_1} \cdot (w_2 - a_{12})^{m_{12}} \cdot \dots \cdot (w_n - a_{1n})^{m_{1n}},$$

and

$$\tilde{Q}_1 = w_1^{\deg_{w_1} Q_1} \cdot w_2^{m_{12}} \cdot \dots \cdot w_n^{m_{1n}} \cdot Q_1 \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right).$$

So, we can take  $m_{11} = \deg_{w_1} Q_1$ . From (10) we derive that

$$\deg_{w_j} \tilde{Q}_1 < m_{1j}, \quad j = 1, \dots, n.$$

When  $0 \leq t \ll 1$ , the system (12) has finite number of zeros in  $\mathbb{C}^n$  which depend on  $t$ . Moreover, (12) does not have infinite roots in  $(\mathbb{P}^1(\mathbb{C}))^n$  (see [23] and [5, Theorems 8.5, 8.6]). As was shown in [23] (see also [5, Theorem 8.5]) the number of zeros (counting multiplicities) is equal to the permanent of the matrix  $(m_{ij})_{1 \leq i, j \leq n}$ .

Consider the cycle

$$\tilde{\Gamma}_h = \left\{ w \in \mathbb{C}^n : \left| h_j \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right) \right| = \varepsilon_j, \quad j = 1, \dots, n \right\}.$$

Compactness of the cycle  $\tilde{\Gamma}_h$  implies that

$$\left| q_j \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right) \right| > \left| t \cdot Q_j \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right) \right|, \quad j = 1, \dots, n$$

for  $t$  small enough.

Therefore,  $\tilde{\Gamma}_h$  is homologous to the sum of the cycles  $\tilde{\Gamma}_{h, \tilde{a}_j}$

$$\begin{cases} \left| 1 - a_{1j_1} \frac{1}{w_1} \right| = \varepsilon_1, \\ \dots \\ \left| 1 - a_{nj_n} \frac{1}{w_n} \right| = \varepsilon_n, \end{cases}$$



obtained from the cycles  $\Gamma_{h,\tilde{a}_J}$  by the substitution  $z_j = \frac{1}{w_j}$ .

The equation

$$\left| 1 - a_{jk_j} \frac{1}{w_j} \right| = \varepsilon$$

defines a circle. Indeed, let us first rewrite it in the form

$$|w_j - a_{jk_j}| = \varepsilon |w_j| \quad \text{or} \quad |w_j - a_{jk_j}|^2 = \varepsilon^2 |w_j|^2.$$

Thus

$$(1 - \varepsilon^2) \left| w_j - \frac{a_{jk_j}}{1 - \varepsilon^2} \right|^2 = \frac{\varepsilon^2 \cdot |a_{jk_j}|^2}{(1 - \varepsilon^2)},$$

or

$$\left| w_j - \frac{a_{jk_j}}{1 - \varepsilon^2} \right|^2 = \frac{\varepsilon^2 \cdot |a_{jk_j}|^2}{(1 - \varepsilon^2)^2}, \quad j = 1, \dots, n.$$

For sufficiently small  $\varepsilon$  the point  $a_{jk_j}$  lies inside this circle, and, therefore,  $\tilde{\Gamma}_{h,\tilde{a}_J}$  is homologous to the cycle  $\tilde{\Gamma}_{h,a_J}$ :

$$\begin{cases} |w_1 - a_{1j_1}| = \varepsilon_1, \\ \dots \\ |w_n - a_{nj_n}| = \varepsilon_n. \end{cases}$$

Here  $a_{kj_k}$  can vanish for some  $k$ .

**Lemma 3.** *The following formula holds for the residue integral (9):*

$$J_\gamma(t) = \frac{(-1)^n}{(2\pi i)^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{d\tilde{F}_1}{\tilde{F}_1} \wedge \dots \wedge \frac{d\tilde{F}_n}{\tilde{F}_n}.$$

*Proof.* The equality (11) yields

$$F_j \left( \frac{1}{w_1}, \dots, \frac{1}{w_n}, t \right) = \left( \frac{1}{w_1} \right)^{m_{j1}} \dots \left( \frac{1}{w_n} \right)^{m_{jn}} \cdot \tilde{F}_j(w, t), \quad j = 1, \dots, n.$$

Then

$$\frac{dF_j \left( \frac{1}{w_1}, \frac{1}{w_2}, \dots, \frac{1}{w_n}, t \right)}{F_j \left( \frac{1}{w_1}, \frac{1}{w_2}, \dots, \frac{1}{w_n}, t \right)} = \frac{d\tilde{F}_j(w, t)}{\tilde{F}_j(w, t)} - \sum_{k=1}^n m_{jk} \cdot \frac{dw_k}{w_k}.$$

Using (11) and taking into account the change of orientation of the space after replacing  $z_j = 1/w_j$ ,  $j = 1, \dots, n$ , one can rewrite the integral  $J_\gamma(t)$  as

$$\begin{aligned} J_\gamma(t) &= \frac{(-1)^n}{(2\pi i)^n} \int_{\tilde{\Gamma}_h} w^{\gamma+I} \cdot \frac{dF \left( \frac{1}{w_1}, \dots, \frac{1}{w_n}, t \right)}{F \left( \frac{1}{w_1}, \dots, \frac{1}{w_n}, t \right)} \\ &= \frac{(-1)^n}{(2\pi i)^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{dF_1}{F_1} \wedge \dots \wedge \frac{dF_n}{F_n} \\ &= \frac{(-1)^n}{(2\pi i)^n} \int_{\tilde{\Gamma}_h} w^{\gamma+I} \left( \frac{d\tilde{F}_1(w)}{\tilde{F}_1(w)} - \sum_{k=1}^n m_{1k} \cdot \frac{dw_k}{w_k} \right) \wedge \dots \wedge \left( \frac{d\tilde{F}_n(w)}{\tilde{F}_n(w)} - \sum_{k=1}^n m_{nk} \cdot \frac{dw_k}{w_k} \right). \end{aligned}$$

All the integrals

$$\int_{\tilde{\Gamma}_h} w^{\gamma+I} \frac{d\tilde{F}_{i_1}(w)}{\tilde{F}_{i_1}(w)} \wedge \dots \wedge \frac{d\tilde{F}_{i_l}(w)}{\tilde{F}_{i_l}(w)} \wedge \frac{dw_{j_1}}{w_{j_1}} \wedge \dots \wedge \frac{dw_{j_{n-l}}}{w_{j_{n-l}}} \quad (13)$$

vanish when  $0 \leq l < n$  and  $\varepsilon_j$  are large enough.

Indeed, when  $\varepsilon_j$ ,  $j = 1, \dots, n$  are sufficiently large, the inequalities

$$|\tilde{q}_j| > |t \cdot \tilde{Q}_j(w)|$$

hold on  $\tilde{\Gamma}_h$ . Therefore

$$\frac{1}{\tilde{F}_j(w)} = \sum_{p=0}^{\infty} \frac{(-1)^p t^p \tilde{Q}_j^p(w)}{\tilde{q}_j^{(p+1)}}. \quad (14)$$

Consequently, the integrals (13) are absolutely convergent series of the integrals

$$\int_{\tilde{\Gamma}_h} w^{\gamma+I} \frac{w^\alpha dw_1 \wedge \dots \wedge dw_n}{\tilde{q}_1^{(p_1+1)} \dots \tilde{q}_{i_l}^{(p_l+1)} \cdot w_{j_{i_1}} \dots w_{j_{n-l}}}.$$

Stokes' theorem and the fact that all the integrands are holomorphic imply vanishing of all these integrals.

Finally, we arrive at

$$J_\gamma(t) = \frac{(-1)^n}{(2\pi i)^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{d\tilde{F}_1}{\tilde{F}_1} \wedge \dots \wedge \frac{d\tilde{F}_n}{\tilde{F}_n}$$

□

Now we state a result from [23] that we will need for further discussion.

Consider a system of algebraic equations in  $\mathbb{C}^n$ :

$$f_j(z) = 0, \quad j = 1, \dots, n. \quad (15)$$

Suppose (15) has finite number of roots in  $\mathbb{C}^n$  and does not have infinite roots in  $(\mathbb{CP}^1)^n$ .

Denote  $m_{jk} = \deg_{z_k} f_j$ . When  $r_1, \dots, r_n$  are sufficiently small, the cycle

$$\Gamma = \{z \in \mathbb{C}^n : |f_1(z)| = r_1, \dots, |f_n(z)| = r_n\}$$

is homologous to the sum of cycles lying in the neighborhood of the roots of (15).

**Lemma 4** (A. Tsikh, [23]). *Under the above assumptions*

$$\int_{\Gamma} \frac{P(z) dz}{f_1(z) \dots f_n(z)} = 0$$

for any polynomial  $P(z)$  such that  $p_j = \deg_{z_j} P \leq m_{1j} + \dots + m_{nj}$  for all  $j = 1, \dots, n$ .

The Lemma was proved using the residue theorem (theorem on a total sum of residues) on a compact complex manifold, namely for example a smooth toric compactification of  $\mathbb{T}^n$ .

**Lemma 5.** Let  $\tilde{\Delta} = \tilde{\Delta}(w, t)$  be the Jacobian of (12) with respect to  $w_1, \dots, w_n$ . Then

$$J_\gamma(t) = \sum_{K \in \mathfrak{R}} (-t)^{\|K\|+n} \sum_J \frac{(-1)^{s(J)}}{\beta(K, J)!} \cdot \frac{\partial^{\|\beta(K, J)\|}}{\partial w^\beta(K, J)} \left[ \tilde{\Delta} \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}^K}{\tilde{q}^{K+I}(J)} \right]_{w=a_j}, \quad (16)$$

where  $K = (k_1, \dots, k_n)$  is multi-index,  $\tilde{Q}^K = \tilde{Q}_1^{k_1} \cdots \tilde{Q}_n^{k_n}$ ,

$$\beta(K, J) = (m_{1j_1}(k_{j_1} + 1) - 1, \dots, m_{nj_n}(k_{j_n} + 1) - 1),$$

$$\beta(K, J)! = \prod_p (m_{pj_p}(k_{j_p} + 1) - 1)!, \text{ and}$$

$$\mathfrak{R} = \{K = (k_1, \dots, k_n) : \text{there exists } \gamma_j \text{ such that } \|K\| < \gamma_j + 2, j = 1, \dots, n\}.$$

The rest of the notations in the statement are as in Theorem 2.

*Proof.* The proof of (16) completely repeats the proof of the formula for  $J_\gamma(t)$  in Theorem 2 except for the finiteness of the sum.

We now show that the summation in the above formulas is over a finite set of multi-indices. To show this, we estimate the degrees in  $w_j$  of the numerator and compare with the corresponding degrees of the denominator of (16).

The degree of the numerator in  $w_j$  is less than or equal to

$$p_j = m_{1j} + \dots + m_{nj} - 1 + \gamma_j + 1 + (m_{1j} - 1)k_1 + \dots + (m_{nj} - 1)k_n.$$

The corresponding degree of the denominator is

$$s_j = m_{1j}(k_1 + 1) + \dots + m_{nj}(k_n + 1).$$

Lemma 4 implies vanishing of all the integrals for which the inequality  $p_i \leq s_i - 2$  holds for all  $j = 1, \dots, n$ , so that

$$\begin{aligned} m_{1j} + \dots + m_{nj} - 1 + \gamma_j + 1 + (m_{1j} - 1)k_1 + \dots + (m_{nj} - 1)k_n \\ \leq m_{1j}(k_1 + 1) + \dots + m_{nj}(k_n + 1) - 2. \end{aligned}$$

After combining similar terms we arrive at

$$\gamma_j + 1 - k_1 - \dots - k_n - 1 \leq -2$$

so

$$\gamma_j + 2 \leq \|K\|.$$

Thus, the only non-zero integrals in (16) are the ones for which  $K$  runs over such set that  $\gamma_j + 2 > \|K\|$  for at least one  $\gamma_j$ .  $\square$

**Lemma 6.** Let  $w_1, \dots, w_s$  where  $w_j = (w_{j1}, \dots, w_{jn})$ ,  $j = 1, \dots, n$  be all the zeros (depending on  $t$ ) of (12) counting multiplicities. Then

$$J_\gamma = (-1)^n \sum_{j=1}^s w_{j1}^{\gamma_1+1} \cdot w_{j2}^{\gamma_2+1} \cdots w_{jn}^{\gamma_n+1}.$$

The number  $s$  of the zeros is equal to the permanent of the matrix  $(m_{ij})_{1 \leq i, j \leq n}$  (see [23] or [5, Theorem 8.5]).

*Proof.* The statement follows from the multidimensional logarithmic residue formula and the theorem on shifted skeleton (see [3, Chapter 3]).  $\square$

Denote by  $z^{(k)}(t) = (z_{k1}(t), \dots, z_{kn}(t))$ ,  $k = 1, \dots, s$ , the zeros of (2) with the functions  $tQ_j$ , where  $Q_j$  are defined by (10). The number of the zeros of this system in  $\mathbb{C}^n$  is finite (see Section 2). Denote by  $p$  the number of zeros (multiplicities taken into account) in  $\mathbb{T}^n$ , that is in  $\mathbb{C}^n$  minus the coordinate axes. Since  $z^{(k)}$  do not lie in coordinate subspaces, then  $z_{km} = 1/w_{km}$ ,  $m = 1, \dots, n$  and therefore we have finite number  $p$  of the zeros,  $p \leq s$ .

Recall that  $\tilde{q}_j$  are the functions

$$\tilde{q}_j = (w_1 - a_{j1})^{m_{j1}} \dots (w_n - a_{jn})^{m_{jn}}$$

and  $\tilde{Q}_j$  are the polynomials

$$\tilde{Q}_j = w_1^{m_{j1}} \dots w_n^{m_{jn}} \cdot Q_j \left( \frac{1}{w_1}, \dots, \frac{1}{w_n} \right).$$

**Theorem 7.** *The following equality holds:*

$$\begin{aligned} & \sum_{j=1}^p \frac{1}{z_{k1}(t)^{\gamma_1+1} \dots z_{kn}(t)^{\gamma_n+1}} \\ &= \sum_{K \in \mathfrak{R}} (-t)^{\|K\|+n} \sum_J \frac{(-1)^{s(J)}}{\beta(K, J)!} \cdot \frac{\partial^{\|\beta(K, J)\|}}{\partial w^\beta(K, J)} \left[ \tilde{\Delta}(t) \cdot w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}^K}{\tilde{q}^{K+I}(J)} \right]_{w=a_J}. \end{aligned}$$

*Proof.* The statement follows from Lemmas 5 and 6. Here we use the notations of Theorem 2, with the corresponding changes.  $\square$

Thus, the power sum of zeros of (12) is a polynomial on  $t$ , and, therefore, the equality in Theorem 7 also holds for  $t = 1$ .

Denote

$$\sigma_{\gamma+I} = \sum_{k=1}^p \frac{1}{z_{k1}^{\gamma_1+1} \dots z_{kn}^{\gamma_n+1}},$$

where  $z^{(k)} = (z_{k1}, \dots, z_{kn}) = (z_{k1}(1), \dots, z_{kn}(1))$ ,  $k = 1, \dots, p$ .

**Theorem 8** (Waring's formulas). *For the system  $f_j = 0$ ,  $j = 1, \dots, n$ , with functions  $f_j$  defined by (2) and  $Q_i$  defined by (10) the following formulas are valid:*

$$\begin{aligned} & \sigma_{\gamma+I} = \sum_{k=1}^p \frac{1}{z_{k1}^{\gamma_1+1} \dots z_{kn}^{\gamma_n+1}} \\ &= \frac{1}{(2\pi i)^n} \sum_{\|K\| \geq 0} (-1)^{\|K\|+n} \sum_J (-1)^{s(J)} \int_{\tilde{\Gamma}_{h, a_J}} \tilde{\Delta} \cdot w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}_1^{k_1} \dots \tilde{Q}_n^{k_n}}{\tilde{q}_1^{k_1+1} \dots \tilde{q}_n^{k_n+1}} dw \\ &= \sum_{K \in \mathfrak{R}} (-1)^{\|K\|+n} \sum_J \frac{(-1)^{s(J)}}{\beta(K, J)!} \cdot \frac{\partial^{\|\beta(K, J)\|}}{\partial w^\beta(K, J)} \left[ \tilde{\Delta} \cdot w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}^K}{\tilde{q}^{K+I}(J)} \right]_{w=a_J}. \end{aligned}$$

*Proof.* The statement of the Theorem is a corollary of Theorem 7. □

Note that in [10] the authors considered algebraic systems and obtained expansions of their solutions into geometric series. Moreover, the authors obtained analogs of Waring's formulas for the systems

$$y_j^{m_j} + \sum_{\lambda \in \Lambda^{(j)} \cup \{0\}} x_\lambda^{(j)} y^\lambda = 0, \quad \lambda_1 + \dots + \lambda_n < m_j, \quad j = 1, \dots, n,$$

where leading homogeneous parts are monomials (here  $\Lambda^{(j)}$  is a finite set of multi-indices).

## 4 Residue integrals and Waring's formulas for transcendental systems

We now consider a more general situation. Let  $f_j$  be entire functions in  $\mathbb{C}^n$  of finite order not greater than  $\rho$  and

$$f_j(z) = \prod_{m=1}^{\infty} f_{j,m}(z), \quad j = 1, \dots, n. \quad (17)$$

Here  $f_{j,m}(z)$  are entire functions in  $\mathbb{C}^n$  of finite order not greater than  $\rho$  admitting expansion into uniformly convergent in  $\mathbb{C}^n$  infinite products with factors of the form

$$f_{j,m}(z) = (q_{j,m} + Q_{j,m}(z)),$$

where  $q_{j,m}(z)$  and  $Q_{j,m}(z)$  are the polynomials defined by (3) and (10) respectively. An entire function of several complex variables is not always decomposable into an infinite product of the functions associated with its zeros (see, e.g., [19]). One could find the sufficient conditions for the existence of such an expansion (in the form of convergence of the distances between the origin and zero sets of the functions  $q_{j,m} + Q_{j,m}(z)$ ) in [20].

Denote by  $z^{(j)} = (z_{j1}, \dots, z_{jn})$ ,  $j = 1, \dots, \infty$ , the zeros of (17) not lying in the coordinate subspaces, counting multiplicities.

We now give a multidimensional Waring's formula for transcendental systems.

**Theorem 9.** *Consider the system  $f_j(z) = 0$ ,  $j = 1, \dots, n$ , with the functions  $f_j$  defined by (17). Then, the following formulas are valid:*

$$\begin{aligned} \sigma_{\gamma+I} &= \sum_{j=1}^{\infty} \frac{1}{z_{j1}^{\gamma_1+1} \dots z_{jn}^{\gamma_n+1}} \\ &= \sum_{K \in \mathbb{R}} (-1)^{\|K\|+n} \sum_S \sum_J \frac{(-1)^{s(J)}}{\beta(K, J)!} \cdot \frac{\partial^{\| \beta(K, J) \|}}{\partial w^{\beta(K, J)}} \left[ \tilde{\Delta} \cdot w_1^{\gamma_1+1} \dots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}^K(s)}{\tilde{q}^{K+I}(J, s)} \right]_{w=a_J}, \end{aligned}$$

where  $\tilde{Q}^K(s) = \tilde{Q}_{1,s}^{k_1} \dots \tilde{Q}_{n,s}^{k_n}$ .

*Proof.* We have

$$\frac{d f_j(z)}{f_j(z)} = \frac{d \prod_{s=1}^{\infty} f_{j,s}(z)}{\prod_{s=1}^{\infty} f_{j,s}(z)} = \sum_{s=1}^{\infty} \frac{d f_{j,s}(z)}{f_{j,s}(z)}.$$

The above series converges uniformly on  $\tilde{\Gamma}_{h,a,J}$ . Thus,  $J_\gamma(1)$  is defined and is equal to the convergent series of the integrals

$$\frac{1}{(2\pi i)^n} \int_{\Gamma_q} \frac{1}{z^{\gamma+I}} \cdot \frac{d f_{1,s_1}(z)}{f_{1,s_1}(z)} \wedge \dots \wedge \frac{d f_{n,s_n}(z)}{f_{n,s_n}(z)},$$

where the summation is taken over the cubes with integer sides, centered at the origin. And, for each such integral the required formula was proved in Theorem 8.

If  $\prod_{s=1}^{\infty} f_{j,s}(z)$  converge absolutely, then their values does not depend on the permutation of their factors. In other words, changing the numbering of the roots does not affect the values of the infinite products of  $f_{j,s}(z)$ . Consequently,  $J_\gamma$  also does not depend on the permutation of its terms. This yields absolute convergence of  $J_\gamma$  and  $\sigma_{\gamma+I}$ .  $\square$

**Remark 10.** *We are now ready to describe the scheme of elimination of unknowns. Consider a system of equations of the form as in Theorems 8 and 9. Let  $s_j$  be the power sums of its roots*

$$s_j = \sigma_{j,\dots,j} = \sum_{k=1}^{\infty} \frac{1}{z_{k1}^j \cdot \dots \cdot z_{kn}^j}, \quad j \geq 1. \quad (18)$$

Now, we need to find an entire function  $f(w)$  of a single variable  $w \in \mathbb{C}$ , such that the power sums of its roots coincide with  $s_i$  (by the Weierstrass theorem). Let the Taylor expansion of this function be

$$f(w) = 1 + b_1 w + \dots + b_k w^k + \dots$$

Since the series in the right hand side of (18) converge absolutely, then  $f$  can be decomposed into an infinite product with respect to its zeros

$$c_j = \frac{1}{z_{k1}^j \cdot \dots \cdot z_{kn}^j}, \quad j \geq 1$$

(Hadamard's formula), which yields that  $f(w)$  is an entire function of at most first order of growth. The analogs of recurrent Newton formulas connecting the coefficients  $b_k$  and the sums  $s_i$  for such functions were given in [5, Chapter 1]. More precisely, Theorem 2.3 in [5] states that

$$\sum_{j=0}^{k-1} b_j s_{k-j} + k b_k = 0, \quad b_0 = 1, \quad k \geq 1.$$

These formulas allow one to find the coefficients of the function  $f(w)$ , whose roots are  $c_i$ . So, the function  $f(w)$  is an analog of the resultant for a system of algebraic equations.

## 5 Examples

Since the power sums in Theorem 9 are multidimensional series, then, clearly, this theorem provides one with a method for computing multidimensional series of such kind. For this purpose, one needs a system such that the power sums of its roots coincide with terms of the given series. Once such a system has been found, the sum of the series can then be computed by means of Theorem 9.

In this section, we consider examples where the described method can be used. In the first example, one can find power sums of roots by applying Theorem 8. Then, in the second example, we consider infinite products of the functions considered in the first example. Using Theorem 9 we then construct a series consisting of the power sums of the roots of the system and find the sum of this series.

**Example 11.** Consider the system in two complex variables

$$\begin{cases} f_1(z_1, z_2) = (1 - a_2 z_2)^2 + a_3 z_1 z_2^2 = 0, \\ f_2(z_1, z_2) = (1 - b_1 z_1)^2 (1 - b_2 z_2) + b_3 z_1^2 z_2 = 0 \end{cases} \quad (19)$$

with real coefficients  $a_i$  and  $b_i$ . For this system,  $Q_1$  and  $Q_2$  are of the form (10). It is not hard to verify that the system (19) has 5 roots  $(z_{j1}, z_{j2})$ ,  $j = 1, 2, 3, 4, 5$ . If  $a_2 \neq b_2$ , then all the roots do not lie in the coordinate hyperplanes.

After the substitution  $z_1 = 1/w_1$ ,  $z_2 = 1/w_2$ , (19) takes the form

$$\begin{cases} \tilde{f}_1 = w_1(w_2 - a_2)^2 + a_3 = 0, \\ \tilde{f}_2 = (w_1 - b_1)^2(w_2 - b_2) + b_3 = 0. \end{cases} \quad (20)$$

The Jacobian  $\tilde{\Delta}$  of (20) is equal to

$$\begin{aligned} \tilde{\Delta} &= \begin{vmatrix} (w_2 - a_2)^2 & 2w_1(w_2 - a_2) \\ 2(w_1 - b_1)(w_2 - b_2) & (w_1 - b_1)^2 \end{vmatrix} \\ &= (w_1 - b_1)^2(w_2 - a_2)^2 - 4w_1(w_1 - b_1)(w_2 - a_2)(w_2 - b_2). \end{aligned}$$

Now, using Theorem 8, we compute the power sums

$$\begin{aligned} \sigma_\gamma &= \sum_{j=1}^5 \frac{1}{z_{j1}^{\gamma_1+1}} \cdot \frac{1}{z_{j2}^{\gamma_2+1}} \\ &= \sum_J (-1)^{s(j)} \sum_{K \in \mathfrak{R}} \frac{(-1)^{\|K\|}}{(2\pi i)^2} \int_{\tilde{\Gamma}_{h,a,J}} \frac{w_1^{\gamma_1+1} \cdot w_2^{\gamma_2+1} \cdot a_3^{k_1} \cdot b_3^{k_2} \cdot \tilde{\Delta} \cdot dw_1 \wedge dw_2}{w_1^{k_1+1} (w_2 - a_2)^{2(k_1+1)} \cdot (w_1 - b_1)^{2(k_2+1)} (w_2 - b_2)^{k_2+1}}. \end{aligned}$$

Here  $\mathfrak{R} = \{K = (k_1, k_2) : \text{there exists } i \text{ such that } \gamma_i + 2 > k_1 + k_2 \text{ for } i = 1, 2\}$ , and  $\tilde{\Gamma}_{h,a,J}$  are the cycles either  $\{|w_1| = r_{11}, |w_2 - b_2| = r_{22}\}$  oriented positively or  $\{|w_2 - a_2| = r_{12}, |w_1 - b_1| = r_{21}\}$  oriented negatively.

In particular, by computing  $J_{(0,0)}$ , we obtain that

$$\sigma_{(1,1)} = 4a_2 b_1 - \frac{a_3 b_2}{(b_2 - a_2)^2} \quad (21)$$

without finding the roots.

**Example 12.** Recall the known expansions of  $\sin z$  into an infinite product and a power series:

$$\frac{\sin \sqrt{z}}{\sqrt{z}} = \prod_{k=1}^{\infty} \left(1 - \frac{z}{k^2 \pi^2}\right) = \sum_{k=0}^{\infty} \frac{(-1)^k z^k}{(2k+1)!}.$$

Both are absolutely and uniformly convergent on any compact subset of the complex plane.

Consider the system

$$\begin{cases} f_1 = \frac{\sin \sqrt{2a_2z_2 - a_2^2z_2^2 - a_3z_1z_2^2}}{\sqrt{2a_2z_2 - a_2^2z_2^2 - a_3z_1z_2^2}} = \prod_{k=1}^{\infty} \left( \left(1 - \frac{a_2z_2}{k^2\pi^2}\right)^2 + \frac{a_3z_1z_2^2}{k^2\pi^2} \right) = 0, \\ f_2 = \frac{\sin \sqrt{b_2z_2 + 2b_1z_1 - 2b_1b_2z_1z_2 - b_1^2z_1^2 + b_1^2b_2z_1^2z_2 - b_3z_1^2z_2}}{\sqrt{b_2z_2 + 2b_1z_1 - 2b_1b_2z_1z_2 - b_1^2z_1^2 + b_1^2b_2z_1^2z_2 - b_3z_1^2z_2}} \\ = \prod_{m=1}^{\infty} \left( \left(1 - \frac{b_1z_1}{m^2\pi^2}\right)^2 \left(1 - \frac{b_2z_2}{m^2\pi^2}\right) + \frac{b_3z_1^2z_2}{m^2\pi^2} \right) = 0. \end{cases} \quad (22)$$

Each function in (22) can be expanded into an infinite product of the functions from (19). The system (22) has infinitely many roots. The assumption  $a_2 \cdot b_2 < 0$  implies that no roots of (22) lie in the coordinate planes.

Using (21), we find that

$$\sigma_{(1,1)} = \sum_{j=1}^{\infty} \frac{1}{z_{j1}} \cdot \frac{1}{z_{j2}} = \sum_{k,m=1}^{\infty} \frac{4a_2b_1}{\pi^4k^2m^2} - \sum_{k,m=1}^{\infty} \frac{a_3b_2}{\pi^2(a_2m^2 - b_2k^2)^2}. \quad (23)$$

Using the formula [22, No. 2, Section 5.1.25]

$$\sum_{k=1}^{\infty} \frac{1}{(k^2 + a^2)^2} = \frac{-1}{2a^4} + \frac{\pi}{4a^3} \coth(\pi a) + \frac{\pi^2}{4a^2} \cdot \frac{1}{\sinh^2(\pi a)}$$

we find the sum of the first series in the right hand side of (23)

$$\sum_{k,m=1}^{\infty} \frac{4a_2b_1}{\pi^4k^2m^2} = \frac{a_2b_1}{9}$$

and, respectively, the sum of the second series in the right hand side of (23)

$$\begin{aligned} \sum_{k,m=1}^{\infty} \frac{a_3b_2}{\pi^2(a_2m^2 - b_2k^2)^2} &= - \sum_{k=1}^{\infty} \frac{a_3}{2\pi^2b_2k^4} \\ &- \sum_{k=1}^{\infty} \frac{a_3}{4\pi\sqrt{-a_2b_2}k^3} \coth(\pi\sqrt{-b_2/a_2}k) - \sum_{k=1}^{\infty} \frac{a_3}{4a_2k^2} \cdot \frac{1}{\sinh^2(\pi\sqrt{-b_2/a_2}k)}. \end{aligned}$$

Here the sum of the first series in the right hand side is

$$\sum_{k=1}^{\infty} \frac{a_3}{2\pi^2b_2k^4} = \frac{a_3\pi^2}{180b_2}.$$

We now compute the sum of the second series. Let  ${}_2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x)$  be a basic hypergeometric series (see, e.g., [22, p. 793]). We use the known formula [22, No. 13, Section 5.2.18]

$$\begin{aligned} \sum_{k=1}^{\infty} \frac{x^{k-1}}{e^{2tk} - 1} &= \frac{1}{x} \sum_{k=1}^{\infty} \frac{x^k}{e^{2tk} - 1} \\ &= \frac{1}{x} \cdot \frac{x}{e^{4t} - 1} {}_2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x) = \frac{1}{e^{4t} - 1} {}_2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x). \end{aligned}$$



Therefore,

$$\begin{aligned}
\sum_{k=1}^{\infty} \frac{\coth(tk)}{k^3} &= \sum_{k=1}^{\infty} \frac{1}{k^3} + 2 \sum_{k=1}^{\infty} \frac{1}{k^3(e^{2ts} - 1)} \\
&= \zeta(3) + 2 \frac{1}{e^{4t} - 1} \int_0^1 \frac{1}{y} dy \int_0^y \frac{1}{v} dv \int_0^v {}_2\Phi_1(e^{2t}, e^{2t}; e^{4t}, u) du \\
&= \zeta(3) + \frac{1}{e^{4t} - 1} \int_0^1 \ln^2 y \cdot {}_2\Phi_1(e^{2t}, e^{2t}; e^{4t}, y) dy. \quad (24)
\end{aligned}$$

In order to find the sum of the third series we rewrite  $\frac{1}{\sinh^2(tk)}$  as

$$\frac{1}{\sinh^2(tk)} = \left( \frac{2}{e^{tk} - e^{-tk}} \right)^2 = \frac{4e^{2tk}}{(e^{2tk} - 1)^2}.$$

Now, since

$$\frac{\partial}{\partial t} \left[ \frac{1}{e^{tk} - 1} \right] = -\frac{2ke^{2tk}}{(e^{2tk} - 1)^2},$$

we have

$$\frac{1}{(e^{2tk} - 1)^2} = -\frac{1}{e^{2tk} - 1} - \frac{1}{2k} \cdot \frac{\partial}{\partial t} \left[ \frac{1}{e^{2tk} - 1} \right].$$

Consequently,

$$\sum_{k=1}^{\infty} \frac{1}{\sinh^2(tk) \cdot k^2} = -\frac{\partial}{\partial t} \left[ \sum_{k=1}^{\infty} \frac{2}{k^3(e^{2tk} - 1)} \right]$$

Thus, using the formula (24), we express the series  $\sigma_{(1,1)}$  in terms of the values of some integrals and known series without calculating the roots of the system.

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